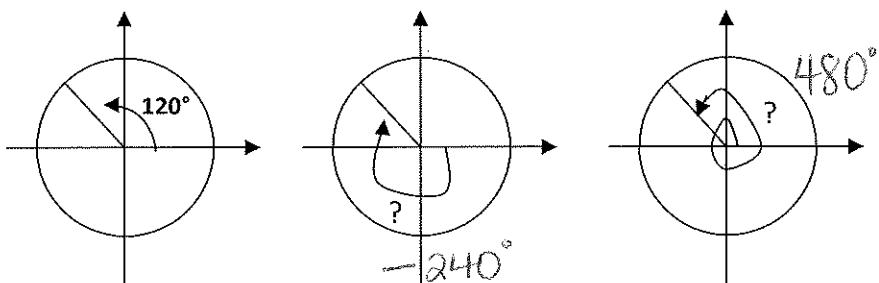


OA: Initial Arm
OP: Terminal Arm



Note: If the rotation is counterclockwise, then $\theta > 0$.

If the rotation is clockwise, then $\theta < 0$.

Definitions: Angles in standard position with the same terminal arm are called **coterminal angles**.

To find coterminal angles, add or subtract multiples of 360° .

$$\theta + 360^\circ n \quad (n \in \mathbb{Z})$$

Reference Angle: The acute angle between the x-axis and the terminal arm.



Primary Trig Functions: Sine, Cosine and Tangent

Reciprocal Trig Functions: Cosecant, Secant and Cotangent

$$\csc \theta = \frac{1}{\sin \theta} \qquad \sec \theta = \frac{1}{\cos \theta} \qquad \cot \theta = \frac{1}{\tan \theta}$$

Ex. 1. Determine each value to 4 decimal places.

a) $\cos 130^\circ = -0.6428$

b) $\sin (-60^\circ) = -0.8660$

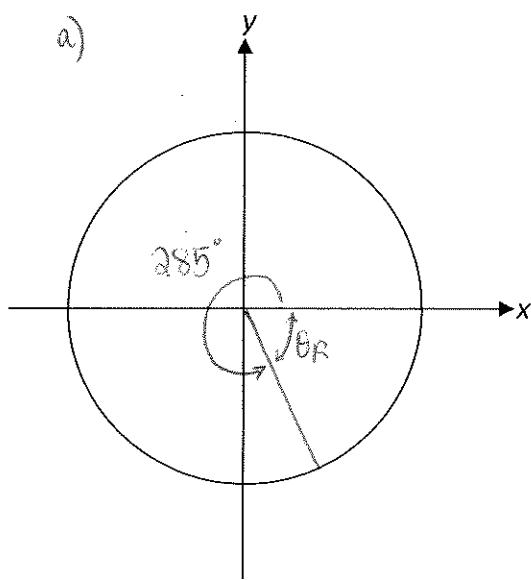
c) $\csc 225^\circ = \frac{1}{\sin 225^\circ} = -1.4142$

d) $\cot (-140^\circ) = \frac{1}{\tan (-140^\circ)} = 1.1918$

Ex. For each angle θ :

- Draw the angle in standard position
- Determine the reference angle
- Determine 2 other angles coterminal with θ
- Write the expression to represent all angles coterminal with θ .

2. $\theta = 285^\circ$



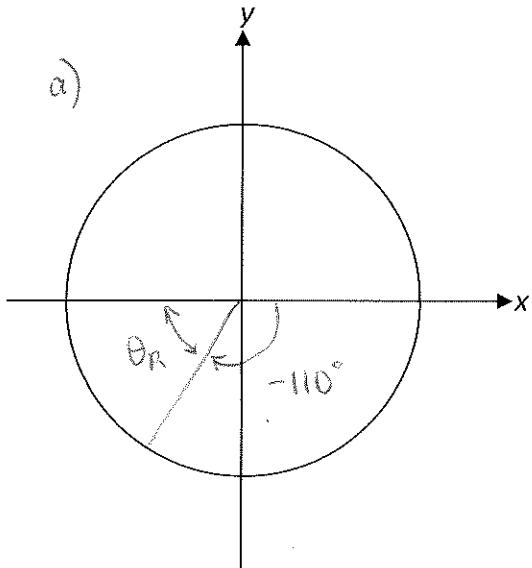
b) $\theta_R = 360^\circ - 285^\circ = 75^\circ$

c) $285^\circ + 360^\circ = 645^\circ$

$285^\circ - 360^\circ = -75^\circ$

d) $285^\circ + 360^\circ n \quad (n \in \mathbb{Z})$

3. $\theta = -110^\circ$



b) $\theta_R = 180^\circ - 110^\circ = 70^\circ$

c) $-110^\circ + 360^\circ = 250^\circ$

$-110^\circ - 360^\circ = -470^\circ$

d) $-110^\circ + 360^\circ n \quad (n \in \mathbb{Z})$